

# STAT 5010 Tutorial 4\*

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## Definitions

1. Let  $\mathfrak{S}$  be a class of decision rules (randomized or nonrandomized). A decision rule  $T \in \mathfrak{S}$  is called  $\mathfrak{S}$ -*admissible* (or *admissible* when  $\mathfrak{S}$  contains all possible rules) if and only if there does not exist any  $S \in \mathfrak{S}$  that is better than  $T$  (in terms of the risk).
2. Now we consider an average of  $R_T(P)$  over  $P \in \mathcal{P}$  :

$$r_T(\Pi) = \int_{\mathcal{P}} R_T(P) d\Pi(P),$$

where  $\Pi$  is a known probability measure on  $(\mathcal{P}, \mathcal{F}_{\mathcal{P}})$  with an appropriate  $\sigma$ -field  $\mathcal{F}_{\mathcal{P}}$ .  $r_T(\Pi)$  is called the *Bayes risk* of  $T$  w.r.t.  $\Pi$ . If  $T_* \in \mathfrak{S}$  and  $r_{T_*}(\Pi) \leq r_T(\Pi)$  for any  $T \in \mathfrak{S}$ , then  $T_*$  is called a  $\mathfrak{S}$ -*Bayes rule* (or *Bayes rule* when  $\mathfrak{S}$  contains all possible rules) w.r.t.  $\Pi$ . The second method is to consider the worst situation, i.e.,  $\sup_{P \in \mathcal{P}} R_T(P)$ . If  $T_* \in \mathfrak{S}$  and  $\sup_{P \in \mathcal{P}} R_{T_*}(P) \leq \sup_{P \in \mathcal{P}} R_T(P)$  for any  $T \in \mathfrak{S}$ , then  $T_*$  is called a  $\mathfrak{S}$ -*minimax* rule (or *minimax* rule when  $\mathfrak{S}$  contains all possible rules).

3. To test the hypotheses  $H_0$  versus  $H_1$ , there are only two types of statistical errors we may commit: rejecting  $H_0$  when  $H_0$  is true (called the *type I error*) and accepting  $H_0$  when  $H_0$  is wrong (called the *type II error*). In statistical inference, a test  $T$ , which is a statistic from  $\mathcal{X}$  to  $\{0, 1\}$ , is assessed by the probabilities of making two types of errors:

$$\alpha_T(P) = P(T(X) = 1) \quad P \in \mathcal{P}_0$$

and

$$1 - \alpha_T(P) = P(T(X) = 0) \quad P \in \mathcal{P}_1,$$

which are denoted by  $\alpha_T(\theta)$  and  $1 - \alpha_T(\theta)$  if  $P$  is in a parametric family indexed by  $\theta$ . Note that these are risks of  $T$  under the 0 – 1 loss in statistical decision theory. However, an optimal decision rule (test) does not exist even for a very simple problem with a very simple class of tests (Example).

4. A common approach to finding an "optimal" test is to assign a small bound  $\alpha$  to one of the error probabilities, say  $\alpha_T(P), P \in \mathcal{P}_0$ , and then to attempt to minimize the other error probability  $1 - \alpha_T(P), P \in \mathcal{P}_1$ , subject to

$$\sup_{P \in \mathcal{P}_0} \alpha_T(P) \leq \alpha.$$

The bound  $\alpha$  is called the *level of significance*. The left-hand side above is called the *size* of the test  $T$ . Note that the level of significance should be positive, otherwise no test satisfies the inequality above except the silly test  $T(X) \equiv 0$  a.s.  $\mathcal{P}$ .

5. For most tests satisfying the inequality above, a small  $\alpha$  leads to a "small" rejection region. It is good practice to determine not only whether  $H_0$  is rejected or accepted for a given  $\alpha$  and a chosen test  $T_\alpha$ , but also the smallest possible level of significance at which  $H_0$  would be rejected for the computed  $T_\alpha(x)$ , i.e.,  $\hat{\alpha} = \inf \{ \alpha \in (0, 1) : T_\alpha(x) = 1 \}$ . Such an  $\hat{\alpha}$ , which depends on  $x$  and the chosen test and is a statistic, is called the *p-value* for the test  $T_\alpha$ .

## Propositions and Theorems

1. (TPE Lemma 5.1.13) If  $\delta_\Lambda$  is the Bayes estimator of  $g(\theta)$  with respect to  $\Lambda$  and if

$$r_\Lambda = E[\delta_\Lambda(\mathbf{X}) - g(\Theta)]^2$$

is its Bayes risk, then

$$r_\Lambda = \int \text{var}[g(\Theta) | \mathbf{x}] dP(\mathbf{x}).$$

In particular, if the posterior variance of  $g(\Theta) | \mathbf{x}$  is independent of  $\mathbf{x}$ , then

$$r_\Lambda = \text{var}[g(\Theta) | \mathbf{x}].$$

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\*Dept. of Stat., CUHK. TA: YX

2. (TPE Theorem 5.1.12) Suppose that  $\{\Lambda_n\}$  is a sequence of prior distributions with Bayes risks  $r_n$  satisfying  $r_n \leq r = \lim_{n \rightarrow \infty} r_n$  and that  $\delta$  is an estimator for which

$$\sup_{\theta} R(\theta, \delta) = r.$$

Then (i)  $\delta$  is minimax and (ii) the sequence  $\{\Lambda_n\}$  is least favorable.

3. For  $X \sim N(\theta, I_p)$  ( $p \geq 3$ ) with  $\theta$  unknown. Under loss  $L(\theta, a) = \|a - \theta\|^2 = \sum_{i=1}^p (a_i - \theta_i)^2$ ,  $X$  is a minimax estimator. But  $X$  is inadmissible and dominated by the James-Stein estimator  $\delta_c = X - \frac{p-2}{\|X-c\|^2}(X-c)$
4. Following the previous proposition, the James-Stein estimator with any  $c$  is still inadmissible and dominated by  $\delta_c^+ = X - \min\{1, \frac{p-2}{\|X-c\|^2}\}(X-c)$ .

## Question 1

1. Let  $X$  be an observation from the Poisson distribution with unknown mean  $\theta > 0$ . Consider the estimation of  $\theta$  under the squared error loss.
- (i) Show that  $\sup_{\theta} R_T(\theta) = \infty$  for any estimator  $T = T(X)$ , where  $R_T(\theta)$  is the risk of  $T$ .
- (ii) Let  $\mathfrak{S} = \{aX + b : a \in \mathcal{R}, b \in \mathcal{R}\}$ . Show that 0 is an admissible estimator of  $\theta$  within  $\mathfrak{S}$ .

**Solution:** See the handout later.